#### Philips Components-Signetics

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Memory Produ	cts

# 27C64A 64K-bit CMOS EPROM (8K × 8)

#### DESCRIPTION

Philips Components—Signetics 27C64A CMOS EPROM is a 65,536-bit 5V read only memory organized as 8,192 words of 8 bits each. It employs advanced CMOS circuitry for systems requiring low power, high-performance speeds, and immunity to noise. The 27C64A has a non-multiplexed addressing interface and is configured in the JEDEC standard EPROM pinout.

Quick-pulse programming is employed on plastic devices which may speed up programming by as much as one hundred times. In the absence of quick-pulse programming equipment, the intelligent programming algorithm may be utilized.

The 27C64A is available in windowed Ceramic DIP, the Plastic DIP and the PLCC packages. This device can be programmed with standard EPROM programmers.

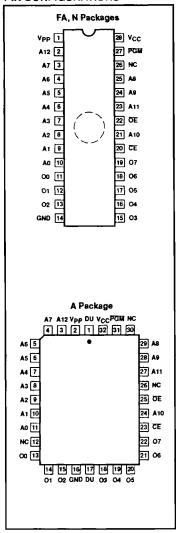
#### **FEATURES**

- Low power consumption
  - 100µA maximum CMOS standby current
- High-performance speed
- 90ns maximum access time
- Noise immunity features
  - ±10% V<sub>CC</sub> tolerance
  - Maximum latch-up immunity through Epitaxial processing
- Quick-pulse programming algorithm

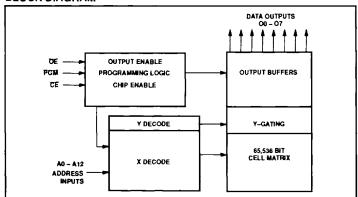
#### PIN DESCRIPTION

IN DECOMM HOM					
A0 - A12	Addresses				
O0 - O7	Outputs				
OE	Output Enable				
CE	Chip Enable				
NC	No Connection				
GND	Ground				
V <sub>PP</sub>	Program voltage				
V <sub>cc</sub>	Power supply				
DU	Don't Use				
PGM	Program strobe				

#### **PIN CONFIGURATIONS**



#### **BLOCK DIAGRAM**



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#### **READ MODE:**

The 27C64A has two control functions, both of which must be logically active in order to obtain data at the outputs. Chip Enable (CE) is the power control and should be used for device selection. Output Enable (OE) is the output control and should be used to gate

data from the output pins. Data is available at the outputs after a delay of  $t_{DC}$  from the falling edge of  $\overline{DC}$ , assuming that  $\overline{CC}$  has been low and addresses have been stable for at least  $t_{ACC}$  -  $t_{DC}$ .

#### STANDBY MODE

The 27C64A has a standby mode which reduces the maximum  $V_{CC}$  current to 100 $\mu$ A. It is placed in the Standby mode when CE is in the High state. When in the Standby mode, the outputs are in a high-impedance state, independent of the  $\overline{OE}$  input.

#### ORDERING INFORMATION

PACKAGE DESCRIPTION	ORDER CODE						
	COMMERCIAL	INDUSTRIAL	AUTOMOTIVE				
28-Pin Ceramic Dual In-Line with quartz window 600mil-wide	27C64A-90 FA 27C64A-12 FA 27C64A-15 FA 27C64A-17 FA 27C64A-20 FA	27C64AI12 FA 27C64AI15 FA 27C64AI20 FA	27C64AA12 FA 27C64AA15 FA 27C64AA20 FA				
28-Pin Plastic Dual In-Line 600mil-wide	27C64A-90 N 27C64A-12 N 27C64A-15 N 27C64A-17 N 27C64A-20 N	27C64Al12 N 27C64Al15 N 27C64Al20 N	27C64AA12 N 27C64AA15 N 27C64AA20 N				
32-Pin Plastic Leaded Chip Carrier 450mil × 550mil	27C64A-90 A 27C64A-12 A 27C64A-15 A 27C64A-17 A 27C64A-20 A	27C64Al12 A 27C64Al15 A 27C64Al20 A	27C64AA12 A 27C64AA15 A 27C64AA20 A				

#### **ABSOLUTE MAXIMUM RATINGS<sup>1</sup>**

SYMBOL	PARAMETER	RATING	UNIT
T <sub>stg</sub>	Storage temperature range	-65 to +125	°C
V <sub>I</sub> . V <sub>O</sub>	Voltage inputs and outputs	-2.0 to (V <sub>CC</sub> + 1)	V
V <sub>H</sub>	Voltage on A9 <sup>2</sup> (During intelligent identifier interrogation)	-2.0 to +13.5	V
V <sub>PP</sub>	Voltage on V <sub>PP</sub> (During programming)	-2.0 to +14.0	V
Vcc	Supply voltage <sup>2</sup>	-2.0 to +7.0	V

#### NOTES:

#### **DEVICE OPERATION<sup>1</sup>**

MODE	CE	ŌΕ	PGM	V <sub>PP</sub> <sup>2</sup>	OUTPUTS
Read	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IH</sub>	V <sub>CC</sub>	Dout
Output Disable	VIL	VIH	VIH	Vcc	Hi-Z
Standby	V <sub>IH</sub>	X <sup>3</sup>	X <sub>3</sub>	Vcc	Hi-Z

#### NOTES:

- 1. All voltages are with respect to network ground.
- V<sub>PP</sub> may be one diode voltage drop below V<sub>CC</sub>, and can be connected directly to V<sub>CC</sub>
- X can be V<sub>IH</sub> or V<sub>IL</sub>.

#### **OPERATING TEMPERATURE RANGE**

PARAMETER	RATING (°C)
	COMMERCIAL 0 to +70
Operating temperature range: T <sub>amb</sub>	INDUSTRIAL -40 to +85
	AUTOMOTIVE -40 to +125

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and
functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not
implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

<sup>2.</sup> All voltages are with respect to network ground.

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## DC ELECTRICAL CHARACTERISTICS Over operating temperature range, +4 5V < Voo < +5 5V

SYMBOL	PARAMETER	TEST CONDITIONS			UNIT		
			MIN	TYP3	MAX	1	
Input currer	nt				<u> </u>	1	
I <sub>IH</sub>	Leakage	V <sub>IN</sub> = 5.5V = V <sub>CC</sub>		0.01	1.0	μА	
I <sub>IL</sub>	Low	V <sub>IL</sub> = 0.45V		0.01	-1.0	μA	
Ірр	V <sub>PP</sub> read	V <sub>PP</sub> = V <sub>CC</sub>			10	μA	
Output curr	ent				<u> </u>	L. '	
ILO	Leakage	OE or CE = V <sub>IH</sub> , V <sub>OUT</sub> = 5.5V = V <sub>CC</sub>	-1.0		1.0	μА	
los	Short circuit <sup>7, 9</sup>	V <sub>OUT</sub> = 0V			100	mA	
Supply curr	ent			-		L	
I <sub>CC</sub> TTL	Operating (TTL inputs) <sup>4, 6</sup>	CE = OE = V <sub>IL</sub> , f = 11.1MHz V <sub>PP</sub> = V <sub>CC</sub> , OO - O7 = 0mA			30	mA	
I <sub>CC</sub> CMOS	Operating (CMOS inputs)4.6	CE = GND, f = 11.1MHz Inputs = V <sub>CC</sub> or GND, I/O = 0mA			15	mA	
I <sub>SB</sub> TTL	Standby (TTL inputs)4	CE = V <sub>IH</sub>			1.0	mA	
I <sub>SB</sub> CMOS	Standby (CMOS inputs) <sup>5</sup>	CE = V <sub>IH</sub>			100	μА	
Input voltag	e <sup>2</sup>				-L		
V <sub>IL</sub>	Low (TTL)	V <sub>PP</sub> = V <sub>CC</sub>	-0.5		0.8	V	
V <sub>IL</sub>	Low (CMOS)	V <sub>PP</sub> = V <sub>CC</sub>	-0.2		0.2	V	
V <sub>IH</sub>	High (TTL)	V <sub>PP</sub> = V <sub>CC</sub>	2.0		V <sub>CC</sub> + 0.5	V	
ViH	High (CMOS)	V <sub>PP</sub> = V <sub>CC</sub>	V <sub>CC</sub> - 0.2		V <sub>CC</sub> + 0.2	v	
V <sub>PP</sub>	Read <sup>8</sup>	(Operating)	V <sub>CC</sub> - 0.7		Vcc	V	
Output volta	ge <sup>2</sup>		1_00_1		• • • • •		
V <sub>OL</sub>	Low	l <sub>OL</sub> = 2.1mA			0.45		
V <sub>OH</sub>	High	I <sub>OH</sub> = -2.5mA	3.5		0.40	v	
Capacitance	9 T <sub>amb</sub> = 25°C				1		
C <sub>IN</sub>	Address and control	V <sub>CC</sub> = 5.0V, f = 1.0MHz	[		6	pF	
Cout	Outputs	V <sub>IN</sub> = 0V, V <sub>OUT</sub> = 0V			12	pF	

- NOTES:

  Minimum DC input voltage is -0.5V. During transitions the inputs may undershoot to -2.0V for periods less than 20ns.

  All voltages are with respect to network ground.

  Typical limits are at V<sub>CC</sub> = 5V, T<sub>amb</sub> = 25°C.

  TTL inputs: Spec V<sub>IL</sub>, V<sub>IH</sub> levels.

  CMOS inputs: GND ± 0.2V to V<sub>CC</sub> ± 0.2V.

  TEL is V<sub>CC</sub> ± 0.2V. All other inputs can have any value within spec.

  Maximum active power usage is the sum of log ± log and is measured at a frequency of 11 1MHz.

- Maximum active power usage is the sum of IPP + ICC and is measured at a frequency of 11.1MHz.
- Test one output at a time, duration should not exceed 1 second.
- 8.  $V_{PP}$  may be one diode voltage drop below  $V_{CC}$ , and can be connected directly to  $V_{CC}$ .
- Guaranteed by design, not 100% tested.

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AC ELECTRICAL CHARACTERISTICS Over operating temperature range, +4.5V  $\leq$  V<sub>CC</sub>  $\leq$  +5.5V, R<sub>L</sub> = 660 $\Omega$ , C<sub>L</sub> = 100pF<sup>4</sup>

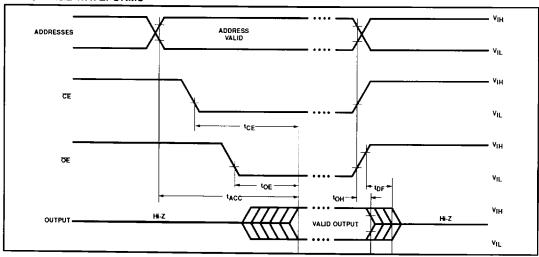
SYMBOL	то	FROM	27C6	4 <b>A</b> -90	27C6	4A-12 4Al12 4AA12	27C6	4A-15 4Al15 4AA15	27C6	4 <b>A</b> -17	27C6	4A-20 4A120 4AA20	UNIT
			MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	1
Access tim	ie <sup>1</sup>	_		•									
t <sub>ACC</sub>	Output	Address		90		120		150		170		200	ns
t <sub>CE</sub>	Output	CE		90		120		150		170		200	ns
t <sub>OE</sub> 3	Output	ŌΕ		40		60		65		70		75	ns
Disable tim	ie <sup>2</sup>			<u> </u>		_					<u> </u>	·	
t <sub>OF</sub>	Output Hi-Z	Œ		25		30		45	Γ	50		55	ns
tон	Output hold	Address, CE or OE	0		0		0		0		0		ns

#### NOTES:

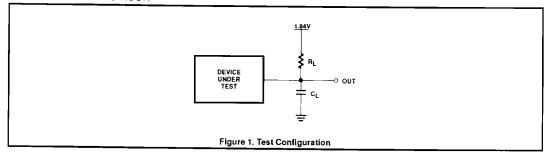
- 1. AC characteristics are tested at  $V_{IH}$  = 2.4V and  $V_{IL}$  = 0.45V. Timing measurements made at  $V_{OL}$  = 0.8V and  $V_{OH}$  = 2.0V.
- 2. Guaranteed by design, not 100% tested.
  3. OE may be delayed up to to: to: after the falling edge of CE without impact on to:

  OE may be delayed up to to: to: after the falling edge of CE without impact on to:
- 4. For 90ns part, CL = 30pF.

#### **AC VOLTAGE WAVEFORMS**



#### **AC TESTING LOAD CIRCUIT**



#### 27C64A

#### PROGRAMMING INFORMATION

Complete programming system specifications for both the intelligent programming method and for the quick-pulse programming method are available upon request from Signetics Memory Marketing.

Signetics encourages the purchase of programming equipment from a manufacturer who has a full line of programming products to offer. Signetics also encourages the manufacturers of EPROM programming equipment to submit their equipment for verification of electrical parameters and programming procedures. Information on manufacturers offering equipment certified by Signetics is available upon request from Signetics.

#### PROGRAMMING THE 27C64A

Caution: Exceeding 14.0V on V<sub>PP</sub> Pin may permanently damage the 27C64A.

Initially, all bits of the 27C64A are in the "1" state. Data is introduced by selectively programming "0"s into the desired bit locations. Although only "0"s will be programmed, both "1"s and "0"s can be present in the data word.

The data to be programmed is applied 8 bits in parallel to the data output pins. The levels required for the address and data inputs are standard TTL logic levels.

## QUICK-PULSE PROGRAMMING ALGORITHM

Signetics plastic EPROMs can be programmed using the quick-pulse programming algorithm to substantially reduce the through-put time in the production environment. This algorithm typically allows plastic devices to be programmed in under four seconds, a significant improvement over previous algorithms. Actual programming time is a function of the EPROM programming equipment being used.

The quick-pulse programming algorithm uses initial pulses of 100µs followed by a byte verification to determine when the address byte has been successfully programmed. Up to 28 100µs pulses per byte are provided before a failure is recognized (refer to the following pages for algorithm specifications).

#### **ERASURE CHARACTERISTICS**

The erasure characteristics of the 27C64A are such that erasure begins to occur upon exposure to light with wavelengths shorter than approximately 4000 Angstroms (A). It should be noted that sunlight and certain types of fluorescent lamps have wavelengths in the 3000 - 4000 Å range. Data shows that constant exposure to room level fluorescent lighting could erase the typical 27C64A in approximately three years, while it would take approximately one week to cause erasure when exposed to direct sunlight. If the 27C64A is to be exposed to these types of lighting conditions for extended periods of time, opaque labels should be placed over the window to prevent unintentional erasure

The recommended erasure procedure for the 27C64A is exposure to shortwave ultraviolet light which has a wavelength of 2537 Angstroms (Å). The integrated dose (i.e., UV intensity × exposure time) for erasure should be minimum of 15Wsec/cm<sup>2</sup>. The erasure time with this dosage is approximately 15 to 20 minutes using an ultraviolet lamp with a 12,000µW/cm2 power rating. The 27C64A should be placed within one inch of the lamp tubes during erasure. The maximum integrated dose a 27C64A can be exposed to without damage is 7258Wsec/cm2 (1 week @ 12000µW/cm2). Exposure of these CMOS EPROMs to high intensity UV light for longer periods may cause permanent damage.

## INTELLIGENT PROGRAMMING ALGORITHM

The 27C64A intelligent programming algorithms rapidly program CMOS EPROMs using an efficient and reliable method particularly suited to the production programming environment. Actual programming times may vary due to differences in programming equipment.

The intelligent identifier also provides the reading out of a binary code from an EPROM that will identify its manufacturer and type. This is intended for use by programming equipment for the purpose of automatically matching the device to be programmed with its corresponding programming algorithm This mode is functional in the 25° ± 5°C ambient temperature range that is required when programming the 27C64A. To activate this mode, the programming equipment must force 11.5V to 12.5V on address A9 of the 27C64A. Two bytes may then be read from the device outputs by toggling address line A0 from VIL to VIH. The CE, OE and all other address lines must be at V<sub>IL</sub> during interrogation.

The identifier information for Signetics 27C64A is as follows:

When A0 =  $V_{IL}$  data is "Manufacturer" 15<sub>(HEX)</sub> When A0 =  $V_{IH}$  data is "Product" 0B<sub>(HEX)</sub>

Programming reliability is also ensured as the incremental program margin of each byte is continually monitored to determine when it has been successfully programmed. The programming algorithm utilizes two different pulse types: initial and overprogram. The duration of the initial PGM pulse(s) is 1ms, which is then followed by a longer overprogram pulse of 3Xms. X is an iteration counter and is equal to the number of the initial 1ms pulses applied to a particular location before a correct verify occurs. Up to 25 1ms pulses per byte are provided for before the overprogram pulse is applied.

When the intelligent programming cycle has been completed, all bytes should be compared to the original data source with  $V_{\rm CC}=5.0 V$  (refer to the following pages for algorithm specifications).

#### CMOS NOISE CHARACTERISTICS

Special epitaxial processing techniques have enabled Signetics to build CMOS with features that add to system reliability. These include input/output protection to latch-up for stresses up to 100mA on Address and Data pins that range from -1V to (V<sub>CC</sub> + 1V). In addition, the V<sub>PP</sub> (Programming) pin is designed to resist latch-up to the 14V maximum device limit

#### SIGNETICS DISCOURAGES THE CONSTRUCTION AND USE OF "HOMEMADE" PROGRAMMING EQUIPMENT

In order to consistently achieve excellent programming yields, periodic calibration of the programming equipment is required. Consult the equipment manufacturer for the recommended calibration interval. Signetics warranty for programmability extends only to product that has been programmed on certified equipment that has been serviced to the manufacturers recommendation.

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#### INTELLIGENT PROGRAMMING ALGORITHM

#### DC PROGRAMMING CHARACTERISTICS

 $T_{amb} = 25^{\circ}C \pm 5^{\circ}C$ ,  $V_{CC} = 6.0V \pm 0.25V$ ,  $V_{PP} = 12.5V \pm 0.5V$ 

SYMBOL	PARAMETER	TEST CONDITIONS	LIN	UNIT	
			MIN	MAX	1
1,	Input current (all inputs)	$V_{IN} = V_{IL}$ or $V_{IH}$		1.0	μΑ
V <sub>IL</sub>	Input low level (all inputs)		-0.1	0.8	V
V <sub>IH</sub>	Input high level		2.4	6.5	V
Vol	Output low voltage during verify	I <sub>OL</sub> = 2.1mA		0.45	V
V <sub>OH</sub>	Output high voltage during verify	I <sub>OH</sub> = -2.5mA	3.5		V
I <sub>CC2</sub>	V <sub>CC</sub> supply current	O0 - 15 = 0mA		50	mA
I <sub>PP2</sub>	V <sub>PP</sub> supply current (program)	CE = V <sub>IL</sub>		50	mA

#### **AC PROGRAMMING CHARACTERISTICS**

SYMBOL	PARAMETER	TEST CONDITIONS		LIMITS		UNIT
			MIN	TYP	MAX	
tas	Address setup time		2			μs
toes	OE setup time		2			μs
t <sub>DS</sub>	Data setup time		2			μs
t <sub>AH</sub>	Address hold time		0			μs
t <sub>DH</sub>	Data hold time		2			μs
t <sub>DFP</sub> 3	OE high to output float delay		0		130	ns
typs	V <sub>PP</sub> setup time		2			μs
tvcs	V <sub>CC</sub> setup time		2			μs
tces	CE setup time		2			μs
t <sub>PW</sub>	CE initial program pulse width	Note 1	0.95	1.0	1.05	ms
topw	CE overprogram pulse width	Note 2	2.85		78.75	ms
t <sub>OE</sub>	Data valid from OE	_			150	μs

#### **AC CONDITIONS OF TEST**

Input Rise and Fall Times (10% to 90%)	20ns
Input Pulse Levels	
Input Timing Reference Level	0.8V and 2.0V
Output Timing Reference Level	0.8V and 2.0V

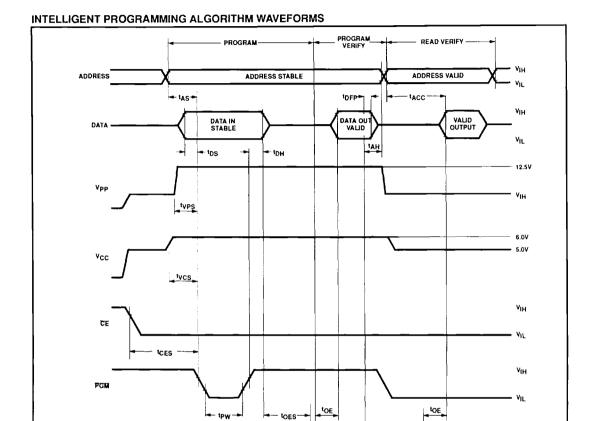
#### NOTES:

- 1. Initial program pulse width tolerance is 1ms  $\pm 5\%$ .
- The length of the overprogram pulse may vary from 2.85msec to 78.75msec as a function of iteration counter value X.
   The parameter is only sampled and is not 100% tested. Output Float is defined as the point where data is no longer driven see timing diagram.
- 4. During programming, a 0.1μf capacitor is required from V<sub>PP</sub> to GND node, to suppress voltage transients that can damage the device.

### 27C64A

 $v_{IH}$ 

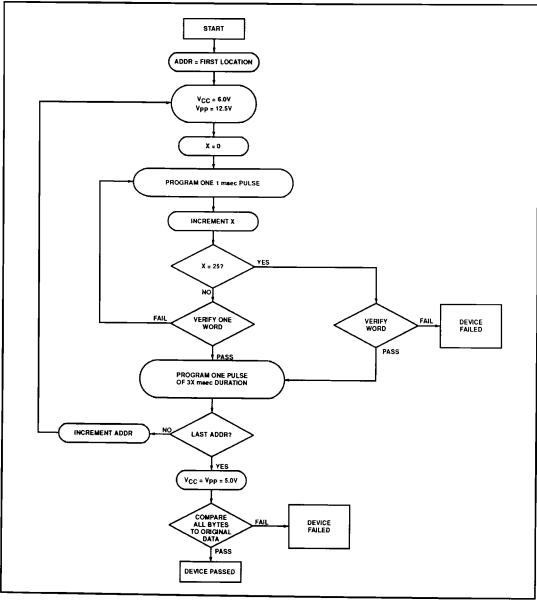
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27C64A

### INTELLIGENT PROGRAMMING ALGORITHM FLOWCHART



27C64A

#### QUICK PULSE PROGRAMMING ALGORITHM

#### DC PROGRAMMING CHARACTERISTICS

 $T_{amb} = 25^{\circ}C \pm 5^{\circ}C$ ,  $V_{CC} = 6.25V \pm 0.25V$ ,  $V_{PP} = 12.75V \pm 0.25V$ 

SYMBOL	PARAMETER	TEST CONDITIONS	LIN	UNIT	
			MIN	MAX	1
l <sub>i</sub>	Input current (all inputs)	$V_{iN} = V_{iL}$ or $V_{iH}$		1.0	μА
VIL	Input low level (all inputs)		-0.1	0.8	V
V <sub>IH</sub>	Input high level		2.4	6.5	V
Vol	Output low voltage during verify	I <sub>OL</sub> = 2.1mA		0.45	V
V <sub>OH</sub>	Output high voltage during verify	I <sub>OH</sub> = -2.5mA	3.5		V
Iccz	V <sub>CC</sub> supply current	O0 - 15 = 0mA		50	mA
l <sub>PP2</sub>	V <sub>PP</sub> supply current (program)	CE = VIL		50	mA
V <sub>PP</sub>	Programming voltage		12.5	13.0	V

#### **AC PROGRAMMING CHARACTERISTICS**

SYMBOL	PARAMETER	TEST CONDITIONS	LIMITS			UNIT
			MIN	TYP	MAX	
tas	Address setup time		2			μs
toes	OE setup time		2			μs
tos	Data setup time		2			μs
t <sub>AH</sub>	Address hold time		0			μs
t <sub>DH</sub>	Data hold time		2			μs
t <sub>DFP</sub> 3	OE high to output float delay		0		130	ns
t <sub>VPS</sub>	V <sub>PP</sub> setup time		2			μs
t <sub>VCS</sub>	V <sub>CC</sub> setup time		2			μs
t <sub>PW</sub>	CE initial program pulse width	Note 1	.095	0.100	0.105	ms
topw	CE overprogram pulse width	Note 2	2.85		78.8	ms
t <sub>OE</sub>	Data valid from OE			1	150	μs

#### **AC CONDITIONS OF TEST**

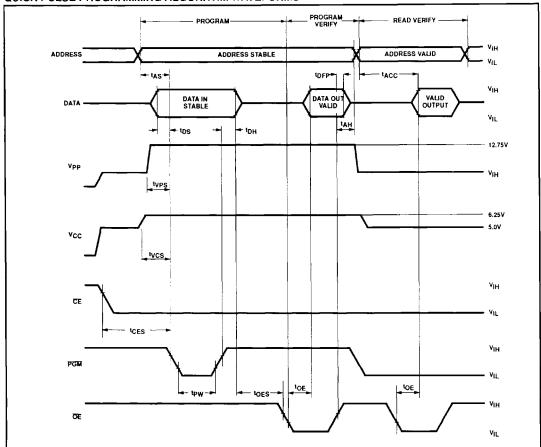
Input Rise and Fall Times (10% to 90%)	20ns
Input Pulse Levels	0.45V to 2.4V
Input Timing Reference Level	0.8V and 2.0V
Output Timing Reference Level	0.8V and 2.0V

#### NOTES:

- 1. Initial program pulse width tolerance is 1ms  $\pm 5\%$ .
- The length of the overprogram pulse may vary from 2.85msec to 78.75msec as a function of iteration counter value X.
   The parameter is only sampled and is not 100% tested. Output Float is defined as the point where data is no longer driven see timing diagram.
- During programming, a 0.1μf capacitor is required from V<sub>PP</sub> to GND node, to suppress voltage transients that can damage the device.

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### QUICK PULSE PROGRAMMING ALGORITHM WAVEFORMS



27C64A

### QUICK PULSE PROGRAMMING ALGORITHM FLOWCHART

